

CONSERVATION LAWS

Axiom 1: Principle of Conservation of Mass

Mass is invariant under the motion. That is,

$$\frac{\mathrm{d}}{\mathrm{d}t}\int_{v}\rho\mathrm{d}v=0\,.\tag{1}$$

Using the Reynolds transport theorem, we find

$$\frac{\partial}{\partial t} \int_{v} \rho dv + \int_{s} \rho \mathbf{v} \cdot d\mathbf{s} = 0 \qquad (\text{Global})$$
⁽²⁾

or

$$\int_{v} \left(\frac{\partial \rho}{\partial t} + (\rho v_k)_{,k} \right) dv = 0.$$
(3)

That leads to the equation of continuity

$$\frac{\partial \rho}{\partial t} + (\rho v_k)_{,k} = 0. \quad (\text{Local})$$
(4)

Axiom 2: Principle of Balance of Linear Momentum

The time rate of change of momentum is equal to the resultant force acting on the body. That is

$$\frac{d}{dt}\int_{v}\rho v_{k}dv = \int_{v}\rho f_{k}dv + \int_{s}t_{k}^{(n)}ds,$$
(5)

where f_k is the acceleration of the body force and $t_k^{(n)}$ is the surface traction force. Using the Reynolds transport equation, we find

$$\frac{\partial}{\partial t} \int_{v} \rho v_{k} dv + \int_{s} \rho v_{k} v_{j} ds_{j} = \int_{v} \rho f_{k} dv + \int_{s} t_{k}^{(n)} ds .$$
(Global) (6)

Introducing the stress tensor $t_{\ell k}$ as

$$\mathbf{t}_{k}^{(n)} = \mathbf{t}_{\ell k} \mathbf{n}_{\ell}, \ \mathbf{t}^{(n)} = \mathbf{n} \cdot \mathbf{t}, \tag{7}$$

ME639

G. Ahmadi



the last term in (6) may be restated as

$$\int\limits_{s} t_{\ell k} n_{\ell} ds = \int\limits_{v} t_{\ell k,\ell} dv \, .$$

Using the divergence theorem in the second term of (6) or noting that $\frac{d}{dt}(\rho d\mathbf{v}) = 0$ in (5), we find

$$\int_{v} (\rho \frac{dv_k}{dt} - \rho f_k - t_{\ell k,\ell}) dv = 0 .$$

This implies that

$$\rho \frac{\mathrm{d}v_{k}}{\mathrm{d}t} = \rho f_{k} + t_{\ell k,\ell} . \quad \text{(Local)}$$
(8)

Axiom 3: Principle of Balance and Angular Momentum

Time rate of change of angular momentum about a fixed point is equal to the resultant moments about that point. That is

$$-\frac{d}{dt}\int_{v}\rho(\sigma_{k}+\varepsilon_{kmj}r_{m}v_{j})dv = \int_{v}\rho\varepsilon_{kmj}r_{m}f_{j}dv + \int_{s}\varepsilon_{kmj}r_{m}t_{j}^{(n)}ds + \int_{s}m_{k}^{(n)}ds + \int_{s}\rho\ell_{k}ds, \quad (9)$$

where σ_k is the inertial spin, r_m is the position, $m_k^{(n)}$ is the surface couple, and ℓ_k is the body couple per unit mass.

Introducing the couple stress $m_{\ell k}$ as

$$\mathbf{m}_{\mathbf{k}}^{(n)} = \mathbf{m}_{\ell \mathbf{k}} \mathbf{n}_{\ell}, \ \mathbf{m}^{(n)} = \mathbf{n} \cdot \mathbf{m}, \tag{10}$$

and applying the divergence theorem, we find

$$\int_{v} \rho(\dot{\sigma}_{k} + \varepsilon_{kmj} r_{m} \dot{v}_{j}) dv = \int_{v} \left[\rho \varepsilon_{kmj} r_{m} f_{j} + (\varepsilon_{kmj} r_{m} t_{\ell j})_{,\ell} + m_{\ell k,\ell} + \rho \ell_{k} \right] dv.$$
(11)

Note that

$$\left(\varepsilon_{\rm kmj}r_{\rm m}t_{\ell j}\right)_{,\ell} = \varepsilon_{\rm kmj}t_{\rm mj} + \varepsilon_{\rm kmj}r_{\rm m}t_{\ell j,\ell}.$$
⁽¹²⁾

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Taking the cross product of \mathbf{r} and equation (8), it follows that

$$\varepsilon_{kmj} r_m \dot{v}_j = \rho \varepsilon_{kmj} r_m f_j + \varepsilon_{kmj} r_m t_{\ell j,\ell} .$$
⁽¹³⁾

Using (12) and (13) in (11), we find

$$\rho \dot{\sigma}_{k} = \rho \ell_{k} + \varepsilon_{kmj} t_{mj} + m_{\ell k,\ell}. \quad \text{(Local)}$$
(14)

Equation (14) is the statement of local conservation of angular momentum for a polar media.

When

$$\sigma_{k} = \ell_{k} = m_{k\ell} = 0, \tag{15}$$

Equation (14) reduces to

$$\varepsilon_{\rm kmj} t_{\rm mj} = 0 , \qquad (16)$$

i.e., the stress tensor must be symmetric for a nonpolar media.

Axiom 4: Principle of Conservation of Energy

Time rate of change of internal and kinetic energy is equal to the rate of work done by the external force and the net heat transferred to the body. That is

$$\frac{\mathrm{d}}{\mathrm{dt}}(\mathrm{K} + \mathrm{E}) = \mathrm{W} + \mathrm{Q}\,. \tag{17}$$

Here, K is the kinetic energy, E is the internal energy, W is the rate of work done, and Q is the rate of heat transfer. Equation (17) may be restated as

$$\frac{d}{dt}\int_{v}\rho\left(e+\frac{1}{2}v_{k}v_{k}\right)dv = \int_{v}\rho v_{k}f_{k}dv + \int_{s}v_{k}\cdot t_{k}^{(n)}ds + \int_{s}q_{k}ds_{k} + \int_{v}\rho rdv , \quad (18)$$

Using the divergence theorem, we find

$$\int_{v} \rho(\dot{e} + v_{k} \dot{v}_{k}) dv = \int_{v} (\rho v_{k} f_{k} + v_{k} t_{\ell k, \ell} + t_{\ell k} v_{k, \ell} + q_{k, k} + \rho r) dv.$$
(19)

Taking the dot product of equation (8) with v_k and subtracting the result from (19), leads to the local form of the conservation of energy. That is



$$\rho \dot{\mathbf{e}} = \mathbf{t}_{\ell k} \mathbf{v}_{\ell,k} + \mathbf{q}_{k,k} + \rho \mathbf{r} \,. \qquad \text{(Local)} \tag{20}$$

In these equations, e is the internal energy density, q_k is the heat flux vector pointing outward, and r is the internal heat source per unit mass.

Axiom 5: Entropy Inequality (Clausius-Duhem)

Time rate of change of the entropy minus the net heat transferred divided by the temperature must be positive. That is,

$$\frac{d}{dt}\int_{v}\rho\eta dv - \int_{s}\frac{q_{k}n_{k}}{T}ds - \int_{v}\frac{\rho r}{T}dv \ge 0,$$
(21)

where η is the entropy density and T is the temperature.

Inequality (21) may be restated as

$$\int_{v} \left(\rho \dot{\eta} - \left(\frac{q_{k}}{T}\right)_{,k} - \frac{\rho r}{T} \right) dv \ge 0, \qquad (22)$$

or

$$\rho\dot{\eta} - \left(\frac{q_k}{T}\right)_{,k} - \frac{\rho r}{T} \ge 0. \qquad (\text{Local})$$
(23)

In summary, the basic conservation laws in vector notation are:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0 \tag{24}$$

$$\rho \frac{\mathrm{d}\mathbf{v}}{\mathrm{d}t} = \rho \mathbf{f} + \nabla \cdot \mathbf{t} , \qquad \mathbf{t} = \mathbf{t}^{\mathrm{T}}$$
(25)

$$\rho \frac{\mathrm{d}\mathbf{e}}{\mathrm{d}\mathbf{t}} = \mathbf{t} : \nabla \mathbf{v} + \nabla \cdot \mathbf{q} + \rho \mathbf{r}$$
(26)

$$\rho \frac{\mathrm{d}\eta}{\mathrm{d}t} - \nabla \cdot \left(\frac{\mathbf{q}}{\mathrm{T}}\right) - \frac{\rho r}{\mathrm{T}} \ge 0 \tag{27}$$



Continuum Thermodynamics and Constitutive Equations

Introducing the Helmholtz free energy function

$$\psi = e - T\eta , \qquad (28)$$

entropy inequality (27) may be restated as

$$\frac{\rho}{T}(\dot{e} - \dot{T}\eta - \dot{\psi}) - (\frac{q_k}{T})_{,k} - \frac{\rho r}{T} \ge 0.$$
(29)

Here, we used

$$\dot{\psi} = \dot{e} - \dot{T}\eta - \dot{T}\dot{\eta} \tag{30}$$

to eliminate $\dot{\eta}$.

Using the energy equation (26) to eliminate \dot{e} in (29), we find

$$\frac{1}{T}\left[-\rho(\dot{\psi}+\eta\dot{T})+t_{\ell k}v_{\ell,k}+\frac{q_kT_{,k}}{T}\right] \ge 0$$
(31)

Inequality (31) is an alternative statement of the Clausius-Duhem inequality.

Constitutive Postulates

Assume that

$$\Psi = \Psi(\mathbf{T}, \boldsymbol{\rho}, \mathbf{d}_{k\ell}, \mathbf{T}_{k}), \tag{32}$$

where

$$d_{k\ell} = \frac{1}{2} (v_{k,\ell} + v_{\ell,k})$$
(33)

is the deformation rate tensor. From (33), it follows that

$$\dot{\Psi} = \frac{\partial \Psi}{\partial T} \dot{T} + \frac{\partial \Psi}{\partial \rho} \dot{\rho} + \frac{\partial \Psi}{\partial d_{k\ell}} \dot{d}_{k\ell} + \frac{\partial \Psi}{\partial T_{,k}} \frac{\dot{T}}{T_{,k}}.$$
(34)

By definition, the thermodynamic pressure is given as



$$p = -\frac{\partial \psi}{\partial \rho^{-1}} = \rho^2 \frac{\partial \psi}{\partial \rho}.$$
(35)

Continuity equation implies that

$$\dot{\rho} = -\rho d_{kk} \,. \tag{36}$$

Thus,

$$\frac{\partial \psi}{\partial \rho} \dot{\rho} = -\frac{p}{\rho} d_{kk} \,. \tag{37}$$

Using (34) and (37) in (31) and collecting terms, we find

$$\frac{1}{T}\left[-\rho(\frac{\partial\psi}{\partial T}+\eta)\dot{T}+(t_{k\ell}+p\delta_{k\ell})d_{k\ell}-\rho\frac{\partial\psi}{\partial T_{k}}\dot{T}_{k}-\rho\frac{\partial\psi}{\partial d_{k\ell}}\dot{d}_{k\ell}+\frac{q_kT_{k}}{T}\right]\geq0$$
(38)

Inequality (38) must hold for all independent variations of \dot{T} , $\frac{\cdot}{T_{,k}}$, $\dot{d}_{k\ell}$, $d_{k\ell}$, and $T_{,k}$. Thus, It follows that

$$\eta = -\frac{\partial \psi}{\partial T}, \qquad (39)$$

$$\frac{\partial \Psi}{\partial T_{,k}} = \frac{\partial \Psi}{\partial d_{k\ell}} = 0, \qquad (40)$$

and (38) reduces to

$$(t_{k\ell} + p\delta_{k\ell})d_{k\ell} + \frac{q_k T_{,k}}{T} \ge 0$$
(41)

Linear Constitutive Equations

The general linear constitutive equations for the stress tensor and the heat flux vector are given as

$$\mathbf{t}_{k\ell} = -\mathbf{p}\delta_{k\ell} + \mathbf{L}_{k\ell ij}\mathbf{d}_{ij},\tag{42}$$

$$\mathbf{q}_{k} = \mathbf{L}_{kj}\mathbf{T}_{,j},\tag{43}$$

Subjected to constraints,

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$$L_{k\ell i j} d_{i j} d_{k\ell} \ge 0, \qquad L_{k j} T_{k} T_{j} \ge 0.$$
 (44)

Here, $L_{k\ell ij}$ and L_{kj} are, respectively, a fourth order and a second order constant tensors.

For an isotropic fluid, **L**'s must be isotropic tensors. The most general forms of isotropic tensors of fourth and second order are:

$$L_{k\ell ij} = \lambda \delta_{k\ell} \delta_{ij} + \mu (\delta_{ki} \delta_{\ell j} + \delta_{kj} \delta_{\ell i}) + \mu_1 (\delta_{ki} \delta_{\ell j} - \delta_{kj} \delta_{\ell i}),$$
(45)

$$\mathbf{L}_{\mathbf{k}\ell} = \mathbf{\kappa} \delta_{\mathbf{k}\ell},\tag{46}$$

where λ , μ , μ_1 , and κ are the material constants that, in general, are functions of temperature.

Using (45) and (46) in (42) and (43) and noting that $d_{k\ell}\,$ is a symmetric tensor, we find

$$\mathbf{t}_{k\ell} = (-\mathbf{p} + \lambda \mathbf{d}_{ii}) \delta_{k\ell} + 2\mu \mathbf{d}_{k\ell}, \tag{47}$$

$$q_k = \kappa T_{,k}. \tag{48}$$

These are Newton's laws of viscosity and Fourier's law of heat conductivity. Inequality (44) imposes the following constraints on the coefficients of viscosity and heat conductivity:

$$3\lambda + 2\mu \ge 0, \ \mu \ge 0, \ \kappa \ge 0. \tag{49}$$

Stokes assumed that

$$\lambda = -\frac{2}{3}\mu \tag{50}$$

so that the pressure is the negative of average normal stresses at t point. Stokes assumption given by Equation (50) leads to $p = -\frac{1}{3}t_{kk}$.

Navier-Stokes Equation

Using (47) in (25), we find

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$$\rho \frac{dv_{k}}{dt} = -p_{,k} + \mu v_{k,jj} + (\lambda + \mu) v_{j,jk} + \rho f_{k}.$$
(51)

For an incompressible fluid,

$$\nabla \cdot \mathbf{v} = 0, \tag{52}$$

and

$$\rho \frac{d\mathbf{v}}{dt} = -\nabla p + \mu \nabla^2 \mathbf{v} + \rho \mathbf{f} .$$
(53)

Equations (52) and (53) are four equations for determining four unknowns \mathbf{v} , p for an incompressible flow.

Energy Equation

Using Equation (48) (for a non-constant κ) in (26), we find

$$\rho \frac{de}{dt} = \nabla \cdot (\kappa \nabla T) + t_{ij} v_{j,i} + \rho r .$$
(54)

Noting that

$$t_{ij}v_{j,i} = -pv_{k,k} + \Phi,$$
(55)

where the dissipation function is defined as

$$\Phi = \lambda \mathbf{v}_{\mathbf{k},\mathbf{k}} \mathbf{v}_{\mathbf{i},\mathbf{i}} + 2\mu \mathbf{d}_{\mathbf{i}\mathbf{j}} \mathbf{v}_{\mathbf{j},\mathbf{i}} \,. \tag{56}$$

Noting that

$$pv_{k,k} = -\frac{p}{\rho}\frac{d\rho}{dt} = \rho\frac{d}{dt}(\frac{p}{\rho}) - \frac{dp}{dt}$$
(57)

and using (56) and (57) in Equation (54), we find

$$\rho \frac{dh}{dt} = \frac{dp}{dt} + \nabla \cdot (\kappa \nabla T) + \Phi + \rho r, \qquad (58)$$

where



$$h = e + \frac{p}{\rho}$$
(59)

is the enthalpy.

For flows with constant properties, assuming the perfect gas relationship

$$dh = c_P dT, \ de = c_v dT, \tag{60}$$

where $c_{\rm p}$ and $c_{\rm v}$ are heat capacities at constant pressure and volume, we find

$$\rho c_{p} \frac{dT}{dt} = \frac{dP}{dt} + \kappa \nabla^{2} T + \Phi + \rho r .$$
(61)

For incompressible fluids, the energy equation becomes

$$\rho c_{v} \frac{dT}{dt} = \kappa \nabla^{2} T + \Phi + \rho r, \qquad (62)$$

where

$$\Phi = \mu (\mathbf{v}_{i,j} + \mathbf{v}_{j,i}) \mathbf{v}_{j,i}$$
(63)

Density Change Due to Temperature Variation

For incompressible fluids, Boussinesq assumed that

$$\rho = \rho_0 (1 - \beta (T - T_0)), \ \beta = \text{const.}$$
(64)

When the body flow is only due to gravity, we have

$$\rho \mathbf{f} = -\rho_0 \mathbf{g} \mathbf{k} \left[1 - \beta (\mathbf{T} - \mathbf{T}_0) \right]. \tag{65}$$

Using (65) in (53), we find

$$\rho_0 \frac{d\mathbf{v}}{dt} = -\nabla p + \mu \nabla^2 \mathbf{v} - \rho_0 g [1 - \beta (T - T_0)] \mathbf{k} .$$
(66)

or

$$\rho_0 \frac{\mathrm{d}\mathbf{v}}{\mathrm{d}t} = -\nabla \hat{\mathbf{P}} + \mu \nabla^2 \mathbf{v} - \rho_0 g\beta (\mathbf{T} - \mathbf{T}_0) \mathbf{k} , \qquad (67)$$

ME639



where we have defined excess pressure beyond hydrostatics as

$$\hat{\mathbf{P}} = \mathbf{p} + \rho_0 \mathbf{g} \mathbf{z} \,. \tag{68}$$

For a general body force, we find

$$\rho_0 \frac{d\mathbf{v}}{dt} = -\nabla \hat{\mathbf{P}} + \mu \nabla^2 \mathbf{v} - \rho_0 \beta (\mathbf{T} - \mathbf{T}_0) \mathbf{f} .$$
(69)

Dimensionless Equations

It is advantageous to express the governing equations in nondimensional forms. We introduce dimensionless quantities:

$$x_{i}^{*} = \frac{x_{i}}{L}, \ \mathbf{v}^{*} = \frac{\mathbf{v}}{U_{\infty}}, \ t^{*} = \frac{tU_{\infty}}{L}, \ \rho^{*} = \frac{\rho}{\rho_{0}},$$
 (70)

$$P^{*} = \frac{\hat{P} - P_{\infty}}{\rho_{0} U_{\infty}^{2}}, \ T^{*} = \frac{T - T_{0}}{\Delta T_{0}}, \ \mathbf{f}^{*} = \frac{\mathbf{f}}{\mathbf{g}}$$
(71)

where L, U_{∞} , ρ_0 and T_0 are length, velocity, density and temperature scales. Using (70), the equations of motion and energy transport in nondimensional form become

$$\frac{\partial \rho^*}{\partial t^*} + \nabla^* \cdot (\rho^* \mathbf{v}^*) = 0, \qquad (72)$$

$$\rho^* \frac{d\mathbf{v}^*}{dt^*} = -\nabla^* P^* + \frac{1}{Re} \nabla^{*2} \mathbf{v}^* - \frac{Gr}{Re^2} T^* \mathbf{f}^*,$$
(73)

$$\rho^* \frac{dT^*}{dt^*} = Ec \frac{dP^*}{dt^*} + \frac{1}{RePr} \nabla^{*2} T^* + \frac{Ec}{Re} \Phi^*.$$
(74)

Here, we have defined the following dimensionless groups:

Reynolds number =
$$\operatorname{Re} = \frac{\rho_0 U_{\infty} L}{\mu}$$
, (75)

Prandtl number =
$$\Pr = \frac{\mu c_{P}}{\kappa}$$
, (76)

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Eckert number:
$$Ec = \frac{U_{\infty}^2}{c_P \Delta T_0}$$
, (77)

Grashof number: Gr =
$$\frac{g\beta\rho_0^2 L^3 \Delta T_0}{\mu^2}$$
 (78)