

INDICIAL NOTATION

Goodarz Ahmadi

Department of Mechanical and Aeronautical Engineering
Clarkson University
Potsdam, NY 13699-5727

Outline

- ▶ Basic Rules
- ▶ Vectors and Tensors
- ▶ Tensor Operation
- ▶ Isotropic Tensors

(Cartesian Tensor)

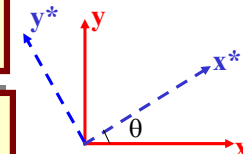
Basic Rules

- A free index appears only once in each term of a tensor equation. The equation then holds for all possible values of that index.
- Summation is implied on an index, which appears twice.
- No index can appear more than twice in any term.

Change of Frame

$$x_i^* = Q_{ij} x_j$$

$$x_j = Q_{ij} x_i^*$$



$$\det|Q_{ij}| = \pm 1$$

$$Q_{ij} Q_{ik} = \delta_{jk}$$

$$Q_{ij} Q_{kj} = \delta_{ik}$$

Definition (Cartesian Tensors) Clarkson University

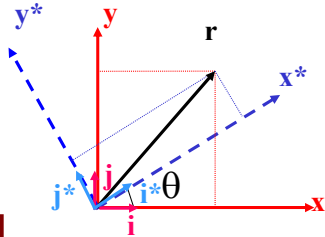
$$\mathbf{r} = x\mathbf{i} + y\mathbf{j} = x^*\mathbf{i}^* + y^*\mathbf{j}^*$$

$$\mathbf{i}^* = \mathbf{i} \cos \theta + \mathbf{j} \sin \theta$$

$$\mathbf{j}^* = -\mathbf{i} \sin \theta + \mathbf{j} \cos \theta$$

$$x^* = x \cos \theta + y \sin \theta$$

$$y^* = -x \sin \theta + y \cos \theta$$



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Definition (Cartesian Tensors) Clarkson University

Transformation in Two Dimension

$$[Q] = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

Kronecker Delta

$$[\delta_{ij}] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

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Definition (Cartesian Tensors) Clarkson University

Scalar

$$T^* = T$$

Vector

$$\mathbf{v}^* = Q \cdot \mathbf{v}$$

Second Order Tensor

$$\boldsymbol{\tau}^* = Q \cdot \boldsymbol{\tau} \cdot Q^T$$

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Vectors and Tensors Clarkson University

Vector

$$v_i^* = Q_{ij} v_j$$

Second Order Tensor

$$t_{ij}^* = Q_{ik} Q_{jl} t_{kl}$$

Third Order Tensor

$$\lambda_{ijk}^* = Q_{im} Q_{jn} Q_{kl} \lambda_{mnl}$$

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Definition (Cartesian Tensors) Clarkson University

Alternating Symbol

$$\longrightarrow \epsilon_{ijk}$$

$$\begin{aligned} \epsilon_{ijk} &= 1, \text{ for } i, j, k \text{ even permutation} \\ \epsilon_{ijk} &= -1, \text{ for } i, j, k \text{ odd permutation} \\ \epsilon_{ijk} &= 0, \text{ when two indices are equal} \end{aligned}$$

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Gradient

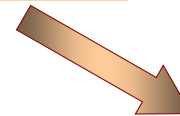


$$\begin{aligned} (\nabla \phi)_i &= \frac{\partial \phi}{\partial x_i} = \phi_{,i} \\ (\nabla \mathbf{v})_{ij} &= \frac{\partial v_j}{\partial x_i} = v_{j,i} \end{aligned}$$

Divergence



$$\nabla \cdot \mathbf{v} = v_{i,i}$$



$$(\nabla \cdot \boldsymbol{\tau})_j = \frac{\partial \tau_{ij}}{\partial x_i} = \tau_{ij,i}$$

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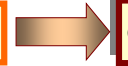
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$$(\nabla \times \mathbf{U})_i = \epsilon_{ijk} \frac{\partial U_k}{\partial x_j} = \epsilon_{ijk} U_{k,j}$$

Determinant



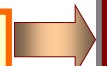
$$\det|\mathbf{A}| = \epsilon_{ijk} A_{1i} A_{2j} A_{3k}$$

Identity



$$\epsilon_{ijk} \epsilon_{imn} = \delta_{jm} \delta_{kn} - \delta_{jn} \delta_{km}$$

Laplacian



$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x_i \partial x_i} = \phi_{,ii}$$

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Rank Zero:



All Scalars

Rank One:



None

Rank Two:



$\alpha \delta_{ij}$

Rank Three:



$\alpha \epsilon_{ijk}$

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Rank Four:

$$\alpha\delta_{ij}\delta_{kl} + \beta(\delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk}) + \gamma(\delta_{ik}\delta_{jl} - \delta_{il}\delta_{jk})$$

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Concluding Remarks Clarkson University

- **Basic Rules**
- **Vectors and Tensors**
- **Tensor Operation**
- **Isotropic Tensors**

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Thank you!

Questions?

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