

# Fokker-Planck Equation

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## Outline

- Ito's Equation
- Fokker-Planck Equation for Ito's Equation
- General Moment Equation
- Example-1<sup>st</sup> Order Non-Linear

**Ito's Equation**

$$\frac{d\mathbf{X}}{dt} = \mathbf{g}(\mathbf{x}, t) + \mathbf{G} \cdot \mathbf{n}$$

$$d\mathbf{X} = \mathbf{g}(\mathbf{x}, t)dt + \mathbf{G}(\mathbf{x}, t) \cdot d\mathbf{W}$$

**with**

$$E\{n_i(t + \tau)n_j(t)\} = 2D_{ij}\delta(\tau)$$

$$E\{dW_i dW_j\} = 2D_{ij}dt$$

The joint density function  $f_{\mathbf{X}}(\mathbf{x}, t)$ , with  $\mathbf{X}(t)$  being solution to Ito's equation, satisfies the Fokker-Planck (Smoluchowski) equation given as :

$$\frac{\partial f}{\partial t} = -\sum_j \frac{\partial}{\partial x_j} (g_j(\mathbf{x}, t)f) + \sum_i \sum_j \frac{\partial^2}{\partial x_i \partial x_j} [(GDG^T)_{ij} f]$$

# Proof

Starting with

$$f(\mathbf{x}, t) = E\{\delta(\mathbf{x}(t) - \mathbf{x})\}$$

Taking time derivative and keeping terms up to first order in  $dt$  (second order in  $dW$ ),

$$\begin{aligned} \frac{\partial f}{\partial t} dt &= \frac{\partial}{\partial t} E\{\delta(\mathbf{X} - \mathbf{x})\} dt \\ &= E\left\{ \sum_j \frac{\partial}{\partial X_j} [\delta(\mathbf{X} - \mathbf{x})] dX_j + \frac{1}{2} \sum_i \sum_j \frac{\partial^2 [\delta(\mathbf{X} - \mathbf{x})]}{\partial X_i \partial X_j} dX_i dX_j \right\} \end{aligned}$$

Using

$$dX_j = g_j(\mathbf{x}, t) dt + \sum_k G_{jk} dW_k$$

# Proof

$$\begin{aligned} \frac{\partial f}{\partial t} dt &= E\left\{ -\sum_j \frac{\partial}{\partial x_j} \left[ \delta(\mathbf{X} - \mathbf{x}) \left( g_j(\mathbf{x}, t) dt + \sum_k G_{jk} dW_k \right) \right] \right. \\ &\quad \left. + \frac{1}{2} \sum_i \sum_j \frac{\partial^2}{\partial x_i \partial x_j} \left[ \delta(\mathbf{X} - \mathbf{x}) \left( g_i(\mathbf{x}, t) dt + \sum_k G_{ik} dW_k \right) \left( g_j dt + \sum_l G_{jl} dW_l \right) \right] \right\} \end{aligned}$$

Noting that  $dW_k$  is independent of  $\mathbf{X}(t)$ , and  $E\{dW_i dW_j\} = 2D_{ij} dt$  it follows that

$$\frac{\partial f}{\partial t} = -\sum_j \frac{\partial}{\partial x_j} (g_j(\mathbf{x}, t) f) + \sum_i \sum_j \frac{\partial^2}{\partial x_i \partial x_j} \left[ f \left( \sum_k \sum_l G_{ik} G_{jl} D_{kl} \right) \right]$$

# Moments of Fokker-Planck Equation

Given Ito's Equation

$$\frac{dX_i}{dt} = g_i(\mathbf{x}, t) + \sum_j G_{ij}(\mathbf{x}, t) \frac{dW_j}{dt} \quad n_i(t) = \frac{dW_i}{dt}$$

$$E\{n_i(t)\} = 0 \quad E\{n_i(t_1) n_j(t_2)\} = 2D_{ij} \delta(t_1 - t_2)$$

Fokker-Planck Equation

$$\frac{\partial f}{\partial t} = -\sum_i \frac{\partial}{\partial x_i} [g_i(\mathbf{x}, t) f] + \sum_i \sum_j \frac{\partial^2}{\partial x_i \partial x_j} \left[ (GDG^T)_{ij} \cdot f \right]$$

# Moments of Fokker-Planck Equation

Expected value of  $h(\mathbf{X})$  is given as

$$E\{h(\mathbf{X})\} = \int_{-\infty}^{+\infty} \dots \int_{-\infty}^{+\infty} h(\mathbf{x}) f(\mathbf{x}, t | \mathbf{x}_0, t_0) f(\mathbf{x}_0, t_0) d\mathbf{x} d\mathbf{x}_0$$

Taking Time Rate of Change

$$\Rightarrow \frac{d}{dt} E\{h(\mathbf{x})\} = \int_{-\infty}^{+\infty} \dots \int_{-\infty}^{+\infty} h(\mathbf{x}) \frac{\partial f}{\partial t} f(\mathbf{x}_0, t_0) d\mathbf{x} d\mathbf{x}_0$$

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Eliminating  $\partial f/\partial t$ ,

$$\frac{d}{dt} E\{h(\mathbf{x})\} = \int_{-\infty}^{+\infty} \dots \int_{-\infty}^{+\infty} \left[ -\sum_i h(\mathbf{x}) \frac{\partial}{\partial x_i} (g_i f) + \sum_i \sum_j h(\mathbf{x}) \frac{\partial^2}{\partial x_i \partial x_j} ((GDG^T)_{ij} f) \right] f(\mathbf{x}_0, t_0) dx_1 dx_0$$

Integrating by parts leads to the general moment equation:

$$\frac{d}{dt} E\{h(\mathbf{x})\} = \sum_i E\left\{ \frac{\partial h}{\partial X_i} g_i(\mathbf{x}, t) \right\} + \sum_i \sum_j E\left\{ (GDG^T)_{ij} \frac{\partial^2 h}{\partial X_i \partial X_j} \right\}$$

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## Example-1st Order NonLinear Equation Clarkson University

Find moment equation corresponding to

$$\dot{X} = -[X(t) + aX^3(t)] + n(t) \quad R_m(\tau) = 2D\delta(\tau)$$

$$\Rightarrow g = -(X + aX^3) \quad G = 1$$

1st Order System

$$\dot{X} = g(X, t) + G(X, t)n(t)$$

$$\Rightarrow \frac{d}{dt} E\{h(X)\} = E\left\{ \frac{\partial h}{\partial X} g \right\} + DE\left\{ G^2 \frac{\partial^2 h}{\partial X^2} \right\}$$

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## Example-1st Order NonLinear Equation Clarkson University

For  $h(X) = X^k \Rightarrow \frac{\partial h}{\partial X} = kX^{k-1} \quad \frac{\partial^2 h}{\partial X^2} = k(k-1)X^{k-2}$

General Moment Equation  $m_k = E\{X^k\}$

$$\dot{m}_k = kE\{X^{k-1}g\} + DE\{G^2 X^{k-2}\}k(k-1)$$

Or

$$\dot{m}_k = -k(m_k + am_{k+2}) + Dk(k-1)m_{k-2}$$

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$$k = 1 \quad \dot{m}_1 = -(m_1(t) + am_3(t))$$

$$k = 2 \quad \dot{m}_2 = -2(m_2(t) + am_4(t)) + 2D$$

$$k = 3 \quad \dot{m}_3 = -3(m_3(t) + am_5(t)) + 6Dm_1$$

A closure assumption is now needed, e.g.,

$$\begin{cases} m_3 = a_0 + a_1 m_1 + a_2 m_2 \\ m_4 = b_0 + b_1 m_1 + b_2 m_2 \end{cases} \quad \text{Coefficients may be estimated by minimizing mean-square error}$$

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## Example-1st Order NonLinear Equation

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$$\begin{cases} \overline{e_1^2} = E\left\{X^3 - a_0 - a_1X - a_2X^2\right\}^2 \\ \overline{e_2^2} = E\left\{X^4 - b_0 - b_1X - b_2X^2\right\}^2 \end{cases}$$

$$\begin{cases} \frac{\partial \overline{e_1^2}}{\partial a_i} = 0 \\ \frac{\partial \overline{e_2^2}}{\partial b_i} = 0 \end{cases} \quad i = 0,1,2$$

Alternative closure scheme assumes  $X(t)$  is quasi-Gaussian

$$\begin{cases} \mu_3 = 0 \\ \mu_4 = 3\mu_2^2 \end{cases}$$

$$\begin{cases} \mu_3 = E\left\{(X - m_1)^3\right\} = m_3 - m_1m_2 - 2m_1^2 \\ \mu_4 = E\left\{(X - m_1)^4\right\} = m_4 - 4m_1m_3 + 6m_1^2m_2 - 3m_1^4 \end{cases}$$

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## Mexico City Earthquake

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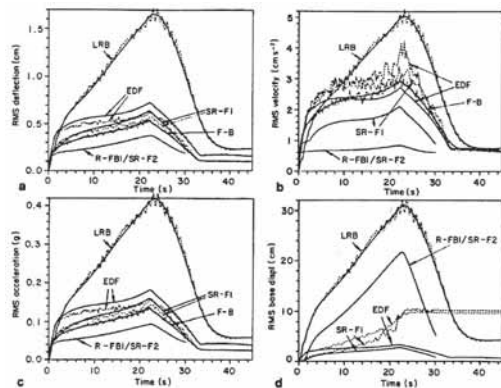


Figure 7. RMS responses for Mexico City 1985 earthquake

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## Fokker-Planck Equation

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### Concluding Remarks

- Ito's Equation
- Fokker-Planck Equation for Ito's Equation
- General Moment Equation
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