

INDICIAL NOTATION

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Outline

- ▶ Basic Rules
- ▶ Vectors and Tensors
- ▶ Tensor Operation
- ▶ Isotropic Tensors

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INDICIAL NOTATION

(Cartesian Tensor)

Basic Rules

- A free index appears only once in each term of a tensor equation. The equation then holds for all possible values of that index.
- Summation is implied on an index, which appears twice.
- No index can appear more than twice in any term.

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Definition (Cartesian Tensors)

Change of Frame

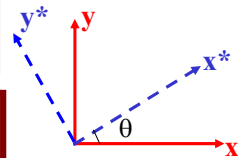
$$X_i^* = Q_{ij} X_j$$

$$X_j = Q_{ij} X_i^*$$

$$\det|Q_{ij}| = \pm 1$$

$$Q_{ij} Q_{ik} = \delta_{jk}$$

$$Q_{ij} Q_{kj} = \delta_{ik}$$



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Definition (Cartesian Tensors)

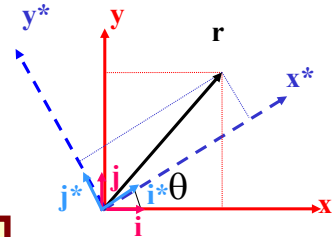
$$\mathbf{r} = x\mathbf{i} + y\mathbf{j} = x^*\mathbf{i}^* + y^*\mathbf{j}^*$$

$$\mathbf{i}^* = \mathbf{i} \cos \theta + \mathbf{j} \sin \theta$$

$$\mathbf{j}^* = -\mathbf{i} \sin \theta + \mathbf{j} \cos \theta$$

$$x^* = x \cos \theta + y \sin \theta$$

$$y^* = -x \sin \theta + y \cos \theta$$



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Transformation in Two Dimension

$$[Q] = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

Kronecker Delta

$$[\delta_{ij}] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

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Scalar

$$T^* = T$$

Vector

$$v^* = Q \cdot v$$

Second Order Tensor

$$\tau^* = Q \cdot t \cdot Q^T$$

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Vector

$$v_i^* = Q_{ij} v_j$$

Second Order Tensor

$$t_{ij}^* = Q_{ik} Q_{jl} t_{kl}$$

Third Order Tensor

$$\lambda_{ijk}^* = Q_{im} Q_{jn} Q_{kl} \lambda_{mnl}$$

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Alternating Symbol

$$\epsilon_{ijk}$$

$$\epsilon_{ijk} = 1, \text{ for } i, j, k \text{ even permutation}$$

$$\epsilon_{ijk} = -1, \text{ for } i, j, k \text{ odd permutation}$$

$$\epsilon_{ijk} = 0, \text{ when two indices are equal}$$

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Gradient

$$(\nabla\phi)_i = \frac{\partial\phi}{\partial x_i} = \phi_{,i}$$

$$(\nabla\mathbf{v})_{ij} = \frac{\partial v_j}{\partial x_i} = v_{j,i}$$

Divergence

$$\nabla \cdot \mathbf{v} = v_{i,i}$$

$$(\nabla \cdot \boldsymbol{\tau})_j = \frac{\partial \tau_{ij}}{\partial x_i} = \tau_{ij,i}$$

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Curl

$$(\nabla \times \mathbf{U})_i = \varepsilon_{ijk} \frac{\partial U_k}{\partial x_j} = \varepsilon_{ijk} U_{k,j}$$

Determinant

$$\det|\mathbf{A}| = \varepsilon_{ijk} A_{1i} A_{2j} A_{3k}$$

Identity

$$\varepsilon_{ijk} \varepsilon_{imn} = \delta_{jm} \delta_{kn} - \delta_{jn} \delta_{km}$$

Laplacian

$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial x_i \partial x_i} = \phi_{,ii}$$

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Rank Zero:

All Scalars

Rank One:

None

Rank Two:

$$\alpha \delta_{ij}$$

Rank Three:

$$\alpha \varepsilon_{ijk}$$

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Rank Four:

$$\alpha \delta_{ij} \delta_{kl} + \beta (\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk})$$

$$+ \gamma (\delta_{ik} \delta_{jl} - \delta_{il} \delta_{jk})$$

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